



## **Instruction manual**

### **TE67X000009637 DeviceNet Module**

**- For transmitting status and weight of digital load cells**

**Instruction manual no.: IM-TE91K014-EN2**

**ESE02424EN**

**Date of issue: September 9, 2014**

**First published: March 8, 2013**

Original manual



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## 2) Introduction

### 2.1 Introduction

This document describes the use of the Alfa Laval Kolding A/S TE67X000009637 DeviceNet communication module, when equipped with program listed on the front page. With this program the TE67X000009637 communication module is capable of transmitting weight and status of up to 4 loadcells in a single telegram. Each loadcell is connected to the communications module through a TE67X000009610 loadcell interfacemodule.

It is possible to connect the TE67X000009637 communication module to DeviceNet, where it will act as a slave. It will then be possible from the DeviceNet master to read status and weight for each of the connected loadcells. Functions as zeroing, calibration and calculation of system weight **must** be implemented on the DeviceNet master.

Exchange of data between DeviceNet master and slave is performed as described in the following.

**Note:** The illustrations and specifications contained in this manual were effective at the date of printing. However, as continuous improvements are our policy, we reserve the right to alter or modify any unit specification on any product without prior notice or any obligation.

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### 2.2 Target group

**Warning:** To avoid operator hazards and damages of the device, the following instructions have to be worked out by qualified technical personnel.



## **2) Introduction (continued)**

### **2.3 Limitation of liability**

By non-observance of the instruction manual, inappropriate use, modification or damage, no liability is assumed and warranty claims will be excluded.

### **2.4 Intended use**

The Alfa Laval TE67X000009637 DeviceNet communication module has, according to the type, been developed for Tank weighing applications. It is the operator's responsibility to check and verify the suitability of the device for the intended application. If any doubts remain, please contact our local Alfa Laval Company in order to ensure proper usage. Alfa Laval Kolding A/S is not liable for any incorrect selections and their effects.

- The technical data listed in the current data sheet are engaging and must be complied with. If the data sheet is not available, please order or download it from our homepage (<http://www.alfalaval.com>)

### 3) Data exchange

#### 3.1 DeviceNet communication using PPO

DeviceNet communication with the TE67X000009637 communication module uses a so called 'parameter-process data object' (PPO) consisting of 26 bytes. This telegram (object) is only used when transferring data from the slave to the master, since no data are transmitted from the master to the slave. The structure for this telegram is as follows:

Lc Register		Lc Status(0)		Lc Weight(0)					Lc Status(3)		Lc Weight(3)			
0	1	2	3	4	5	6	7		20	21	22	23	24	25

The byte order (MSB/LSB first?) for the individual parts of the telegram is determined by jumper JU3. Normally this jumper is set from the factory so that LSB comes first. In the following bit 0 will represent the least significant bit in a register.

**LcRegister** is two bytes that constitute a bit register for indication of connected loadcells detected during power on. Hence bit 0-3 will be ON, if the corresponding loadcell (address) was detected during power on.

**LcStatus(X)** is two bytes that constitute a register containing the actual status for loadcell X. The individual bits in the status register have the following function:

### 3) Data exchange (continued)

<b>BIT-NO</b>	<b>FUNCTION</b>
0	<b>Invalid/missing 'sample' ID</b> Bad connection between communicationsmodule and loadcell module. Not all telegrams from the communicationsmodule are received in the LC module.
1	<b>Timeout – Loadcell not connected ?</b> Check that the loadcell is connected to the loadcell module.
2	<b>Loadcell not synchronised</b> Bad connection between loadcell and loadcell module or very heavy over- or underload.
3	<b>Hardware synchronisation error</b> Loadcell samplings are not synchronised.
4	<b>Power failure</b> The supply voltage is to low.
5	<b>Overflow in weight calculation</b> Internal error in loadcell module.
6	<b>Invalid/missing 'latch' ID</b> Bad connection between communicationsmodule and loadcell module. Not all telegrams from the communicationsmodule are received in the loadcell module.
7	<b>No answer from loadcellmodule</b> No data are received from this loadcell module. This can be caused by the removal of the loadcell module, no power to the module or that the connection between loadcell module and communicationsmodule is broken.

**LcWeight(X)** is four bytes constituting a register containing the actual weight signal from loadcell **X** in gram. Depending on JU4 the weight will be in the following format:

JU4=OFF:                      in "32 bit signed integer" format.  
 JU4=ON:                        in "IEEE754" format.

Since only status and weight for the loadcells are transmitted in the telegram functions such as status handling, calculation of system weight, zeroing and calibration **must** be implemented on the DeviceNet master.

Calculation of system weight is done by addition of the weight registers for the connected loadcells. Note that the result is only valid if all status registers for the connected loadcells indicate **no** errors. It should also be noted that it is up to the master to ensure the usage of consistent loadcell data when calculating the system weight (the used data should come from the same telegram).

### 3) Data exchange (continued)

#### 3.2 IEEE754 format

If by usage of JU4 representation of data on IEEE754 format is selected this is done as follows:

Byte1 (MSB)			Byte2			Byte3		Byte4 (LSB)	
bit7	bit6	bit0	bit7	bit6	bit0	bit7	bit0	bit7	bit0
S	$2^7$	..... $2^1$	$2^0$	$2^{-1}$	..... $2^{-7}$	$2^{-8}$	..... $2^{-15}$	$2^{-16}$	..... $2^{-23}$
Sign	Exponent		Mantissa			Mantissa		Mantissa	

Byte1 (MSB)			Byte2			Byte3		Byte4 (LSB)	
bit7	bit6	bit0	bit7	bit6	bit0	bit7	bit0	bit7	bit0
S	$2^7$	..... $2^1$	$2^0$	$2^{-1}$	..... $2^{-7}$	$2^{-8}$	..... $2^{-15}$	$2^{-16}$	..... $2^{-23}$
Sign	Exponent		Mantissa			Mantissa		Mantissa	

Formula:

$$\text{Value} = (-1)^S * 2^{(\text{exponent}-127)} * (1+\text{Mantissa})$$

Example:

Byte1            Byte2            Byte3            Byte4  
 0100 0000      1111 0000      0000 0000      0000 0000

$$\text{Value} = (-1)^0 * 2^{(129-127)} * (1 + 2^{-1} + 2^{-2} + 2^{-3}) = 7.5$$

Please note that if MSB first has been selected using JU3 the byte with the “sign” will come first in the weight indications, and if LSB first has been selected the byte with the “sign” will come last in the weight indications.

## 4) Zeroing and calibration

### 4.1 Zeroing procedure

Zeroing of the system (all loadcells) should be performed as follows:

- 1) The weighing arrangement should be empty and clean.
- 2) The DeviceNet master reads and stores the actual weight values for the connected loadcells in corresponding zeroing registers.
- 3) After this the actual weight for loadcell **X** can be calculated as:

$$\text{LcGross}(\mathbf{X}) = \text{LcWeight}(\mathbf{X}) - \text{LcZero}(\mathbf{X})$$

and the system weight (uncalibrated) for the connected loadcells is calculated as:

$$\text{SystemWeight} = \text{LcGross}(0) + \text{LcGross}(1) + \dots$$

### 4.2 Calibration procedure

Fine calibration of the system should be performed as follows:

- 1) Check that the weighing arrangement is empty, and that the gross weight is zero. Zero if necessary.
- 2) Place a known load (calibrationweight) on the weighing arrangement.
- 3) Calculate the calibrationfactor that should be multiplied on the system weight in order to achieve correct showing as:

$$\text{Calibrationfactor} = (\text{Calibrationweight})/(\text{Actual showing})$$

After this the determined calibration factor is used to calculate the calibrated weight as follows:

$$\text{Sys.Weight}(\text{Calibrated}) = \text{Calibrationfactor} * \text{Sys.Weight}(\text{Uncalibrated})$$

If the determined calibrationfactor falls outside the interval 0.9 to 1.1 it is very likely that there is something wrong with the mechanical part of the system.

## 5) Installation of system

### 5.1 Checklist during installation

During installation of the system the following should be checked:

- 1) If necessary the DeviceNet master should be configured to communicate with the DeviceNet module (TE67X000009637) using the supplied EDS file.
- 2) The loadcells are mounted mechanically and connected to the DeviceNet module (TE67X000009637) using their corresponding loadcell interface module (TE67X000009610). The loadcell addresses are set using the DIP-switches (Sw1.5-Sw1.8) on the TE67X000009610 modules, so that they forth running from address 0 (0-3).
- 3) The DeviceNet module (TE67X000009637) is connected to the DeviceNet, and possibly a termination is made at this DeviceNet slave.
- 4) The baudrate of the DeviceNet module (TE67X000009637) is set using Sw2.1-Sw2.2 and its address is set using Sw2.3- Sw2.8. Power is applied and the DeviceNet communication is started.
- 5) Verify that the yellow LED (D1) on the DeviceNet module (TE67X000009637) is lit, and that the red LED (D2) is not lit. Verify that the TXBB LED on the DeviceNet module is lit and that the TXBB LED's on the loadcell modules (TE67X000009610) are also lit (can flash slightly). Verify that both the MS and NS LED's end up being lit green constantly.
- 6) Verify that the DeviceNet module (TE67X000009637) has found the correct loadcells (**LcRegister**), and that no loadcell errors are indicated (**LcStatus(x)**).
- 7) Verify that every loadcell gives a signal (**LcWeight(x)**) by placing a load directly above each loadcell one after the other (possibly with a known load).

The system is now installed and a a possible zero and fine calibration is made as described earlier. Finally verify that the weighing system(s) returns a value corresponding to a known actual load.

Note that in the above checklist no consideration has been made on which functions are implemented on the DeviceNet master.

## 6) TE67X000009637 hardware description

### 6.1 DIP-switch settings

The TE67X000009637 module is equipped with two DIP-switch blocks. DIP-switch block 1 has the following function:

SWITCH	FUNCTION
Sw1.1-Sw1.4	Reserved for future use

DIP-switch block 2 has the following function:

SWITCH	FUNCTION
Sw2.1-Sw2.2	<b>Setting of DeviceNet DataRate (DR)</b> The desired baudrate is set according to the table shown below. Note that these switches are only read during power-on.
Sw2.3-Sw2.8	<b>Setting of DeviceNet Node Address (NA)</b> The address (0-63) is set as the DIP-switches are binary coded, so that Sw2.8 is LSB and Sw2.3 is MSB. Note that these switches are only read during power-on.

The baudrate of the TE67X000009637 module is set according to this table:

Sw2.2	Sw2.1	Baudrate
OFF	OFF	125 kbps
ON	OFF	250 kbps
OFF	ON	500 kbps
ON	ON	Not allowed

## 6) TE67X000009637 hardware description (continued)

### 6.2 Jumpers

The TE67X000009637 module is equipped with 5 internal jumpers. These jumpers have the following function:

JUMPER	FUNCTION
JU2	<b>Test mode</b> JU2 OFF: Normal mode (Default at delivery. Should'nt be changed) JU2 ON: Test mode The jumper <u>must</u> be OFF during normal operation.
JU3	<b>Selection of LSB/MSB data format</b> The jumper determines the byte order in which data are transmitted/received. JU3 OFF: LSB first (normal setting from factory) JU3 ON: MSB first
JU4	<b>Selection of (32 Bit Signed Integer) / (IEEE754) data format</b> The jumper determines if the weight indications in the telegram are in 32 bit signed integer or in IEEE754 floating point format. JU4 OFF: 32 bit signed integer format (normal setting from factory) JU4 ON: IEEE754 floating point format
JU5	<i>Reserved for future use</i>
JU6	<b>Test mode</b> JU6 OFF: Normal mode (Default at delivery. Should'nt be changed) JU6 ON: Test mode The jumper <u>must</u> be OFF during normal operation.

## 6) TE67X000009637 hardware description (continued)

### 6.3 Light emitting diodes

The TE67X000009637 module is equipped with 6 light emitting diodes (LED's). These LED's have the following function:

LED	FUNCTION
TxBB (Green LED)	<b>Communication with loadcells</b> The TE67X000009637 communicates with the loadcells
D1 (Yellow LED)	<b>DeviceNet Voltage Detected</b> The TE67X000009637 module has detected DeviceNet voltage on the DeviceNet connector.
D2 (Red LED)	<i>Reserved for future use</i>
TxCAN (Green LED)	<b>CAN bus TxD (Transmit Data)</b> The TE67X000009637 module transmits data across the CAN bus.
MS (Green/Red LED)	<b>Module Status LED</b> The TE67X000009637 Module Status LED, that can be lit/flashing in different colours depending on the status of the module. The function of the MS LED is given in the table below.
NS (Green/Red LED)	<b>Network Status LED</b> The TE67X000009637 Network Status LED, that can be lit/flashing in different colours depending on the status of the network. The function of the NS LED is given in the table below.

Please note that the LED's will flash shortly during power-up during the selftest of the module. The MS and NS LED's will shortly flash Green/Red. The MS and NS LED's can in conjunction with the table below be used for error finding.

## 6) TE67X000009637 hardware description (continued)

Light emitting diode	Colour	Status	Description
MS	Green	ON	<b>Normal Operation.</b> Communication performed normally.
		Flashing	<b>Standby State.</b> The unit needs supervision.
	Red	ON	<b>Unrecoverable fault.</b> A timer error, memory error or other system error. The unit may need replacing.
		Flashing	<b>Recoverable fault.</b> Configuration error, DIP-switch not set correct or similar error. Correct error and restart unit.
	---	OFF	<b>No power.</b> The power is disconnected or the unit is being restarted.
NS	Green	ON	<b>On-Line, Connection OK.</b> The unit is On-Line and a connection with the master has been established.
		Flashing	<b>On-Line, No Connection.</b> The unit is On-Line but no connection to the master has been established.
	Red	ON	<b>Critical Communication Error.</b> The unit has detected an error that makes it impossible to communicate on the network (duplicate MAC Id or Bus-Off error).
		Flashing	<b>Communication Time-Out.</b> One or more I/O connections are in the Time-Out state.
	---	OFF	<b>No power/Off-line.</b> The device may not be powered.

## 6) TE67X000009637 hardware description (continued)

### 6.4 EE-bus connector

The TE67X000009637 module is equipped with a 10 pole connector for connection to the Alfa Laval Kolding A/S EE-bus. Hereby connection to the individual TE67X000009610 loadcell modules as well as to the power supply for the TE67X000009637 module is achieved. The connection is made using a flat cable with mounted connectors for the individual modules. The 10 pole connector has the following connections:

<u>J4 Connector</u>	<u>Function</u>
J1.1-J1.2	RS485-B ( <b>negative</b> line)
J1.3-J1.4	RS485-A ( <b>positive</b> line)
J1.5-J1.6	0VDC (Gnd1)
J1.7-J1.8	+24VDC (Vin1)
J1.9-J1.10	I/O line

### 6.5 DeviceNet connector

The TE67X000009637 module is equipped with a 5 pole connector for connection to DeviceNet. The connection is according to the DeviceNet specification and is made as follows:

<u>J2 Connector</u>	<u>Function</u>	<u>Colour</u>
J2.1	V-	(Black)(0VDC input)
J2.2	CAN_L (Blue)	
J2.3	SHIELD	(Grey)
J2.4	CAN_H (White)	
J2.5	V+	(Red)(24VDC input)

## **7) Maintenance, Service / Repair & Warranty**

### **7.1 Maintenance**

This device is maintenance-free, but to ensure optimum accuracy of the weighing installation it is recommended to inspect the weighing system installation at regular intervals.

Recommended inspection points are:

1: Verify that tank is freestanding. Are all pipe connections flexible and not restraining vertical movement of the tank?

1a: Verify that no changes have been done to the tank? If any modifications has been performed ensure that they are done correctly according to installation recommendations for weighing systems.

2: Verify that all legs of the tanks all are in physical contact with load cells.

2a: on analog output module (TE67X000002029), verify that load from the empty tank is evenly distributed between the legs, load on each leg can be read-out through parameter "LCx mode". If load is unevenly distributed check and re adjust tank legs to ensure even load distribution.

### **7.2 Service / Repair**

#### **7.2.1 Return**

Upon every return of the device, no matter if for recalibration, modifications or repair, it is necessary to contact your local Alfa Laval office to guarantee a quick execution of your request.

Please inform us by sending an email to: [Alteq.PartsandService@alfalaval.com](mailto:Alteq.PartsandService@alfalaval.com). Include the number of devices sent and request a Return Number. Afterwards clean the device, pack it shatterproof and send it to Alfa Laval Kolding A/S indicating the Return Number.

### **7.3 Warranty conditions**

The warranty conditions are subject to the legal warranty period of 12 months from the date of delivery. In case of improper use, modifications of or damages to the device, we do not accept warranty claims. Damaged diaphragms will also not be accepted. Furthermore, defects due to normal wear are not subject to warranty services.

## **8) How to contact Alfa Laval Tank Equipment**

For further information please feel free to contact:

### **Alfa Laval Tank Equipment**

#### **Alfa Laval Kolding A/S**

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