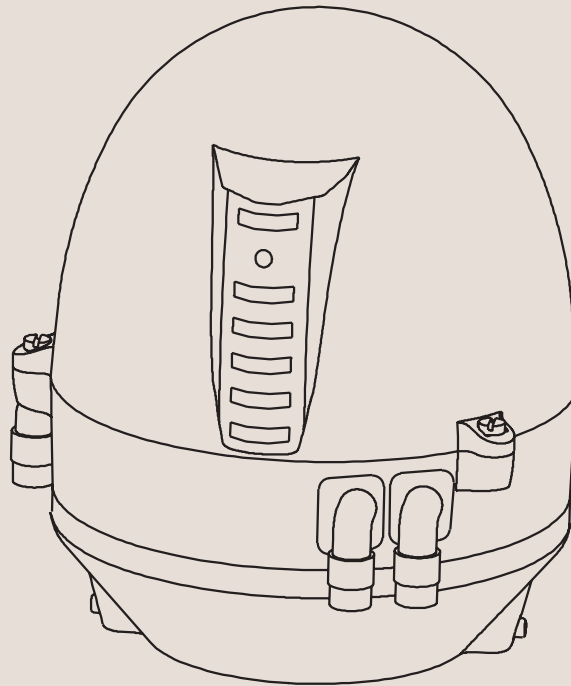




Instruction Manual

ThinkTop® AS-Interface 29.5 - 31.6 VDC



Patented Sensor System
Registered Design
Registered Trademark

Declaration of Conformity

The designating company

Alfa Laval

Company Name

Albuen 31, DK-6000 Kolding, Denmark

Address

+45 79 32 22 00

Phone No.

hereby declare that

Top Unit for Valve Control & Indication

Denomination

ThinkTop® AS-Interface

Type

Year

is in conformity with the following directives with amendments:

- Low Voltage Directive 73/23/EEC
- EMC Directive 89/336/EEC

Vice President, R & D

Title

Bjarne Søndergaard

Name

Alfa Laval

Company



Signature

Designation



The information contained herein is correct at the time of issue but may be subject to change without prior notice.

| | |
|--|-----------|
| 1. Safety | 6 |
| 1.1 Important information | 6 |
| 1.2 Warning signs | 6 |
| 1.3 Safety precautions | 6 |
| 2. General information | 7 |
| 2.1 AS-Interface in general | 7 |
| 3. Technical specifications | 8 |
| 3.1 <i>ThinkTop</i> [®] , AS-Interface 29.5 - 31.6 VDC | 8 |
| 4. Installation | 13 |
| 4.1 Installation on air actuators | 13 |
| 4.2 Installation on Series 700 valves | 16 |
| 4.3 Air connections | 17 |
| 4.4 Electrical connection, internal | 18 |
| 5. Setup diagram | 20 |
| 5.1 <i>ThinkTop</i> [®] setup utilising IR keypad | 20 |
| 5.2 <i>ThinkTop</i> [®] setup utilising local 'I' and 'II' keys | 22 |
| 6. Fault finding | 24 |
| 6.1 Fault finding and LEDs | 24 |
| 7. Maintenance | 26 |
| 7.1 Dismantling of <i>ThinkTop</i> [®] | 26 |
| 7.2 Assembly of <i>ThinkTop</i> [®] | 28 |
| 7.3 Dismantling and assembly of Series 700 valves | 30 |
| 8. Parts list | 32 |
| 8.1 <i>ThinkTop</i> [®] AS-Interface 29.5-31.6 VDC | 32 |
| 8.2 <i>ThinkTop</i> [®] Series 700 valves | 34 |

1.1 Important information

1.2 Warning signs

1.3 Safety precautions

Unsafe practices and other important information are emphasized in this manual.

Warnings are emphasized by means of special signs.

All warnings in the manual are summarized on this page.

Pay special attention to the instructions below so that severe personal injury or damage to the top unit are avoided.

Always read the manual before using the top unit!

WARNING!

Indicates that special procedures **must** be followed to avoid severe personal injury.

CAUTION!

Indicates that special procedures **must** be followed to avoid damage to the *ThinkTop*[®].

NOTE!

Indicates important information to simplify or clarify practices.

General warning:



Dangerous electrical voltage:



Caustic agents:



Installation

- **Always** observe the technical specifications (see chapter 3).
- **Never** install the *ThinkTop*[®] before valve or relay is in a safe position.
- If welding close to the *ThinkTop*[®]: **Always** earth close to the welding area.
- Disconnect the *ThinkTop*[®].
- **Always** have the *ThinkTop*[®] electrically connected by authorized personnel.



Maintenance

- **Always** read the technical specifications thoroughly (see chapter 3).
- **Always** fit the seals between valve and *ThinkTop*[®] correctly.
- **Never** service the *ThinkTop*[®] before valve or relay is in a safe position.
- **Never** service the *ThinkTop*[®] with valve/actuator under pressure.
- **Never** clean the *ThinkTop*[®] with high pressure cleaning equipment.
- **Never** use cleaning agents when cleaning the *ThinkTop*[®]. Check with cleaning agent supplier.



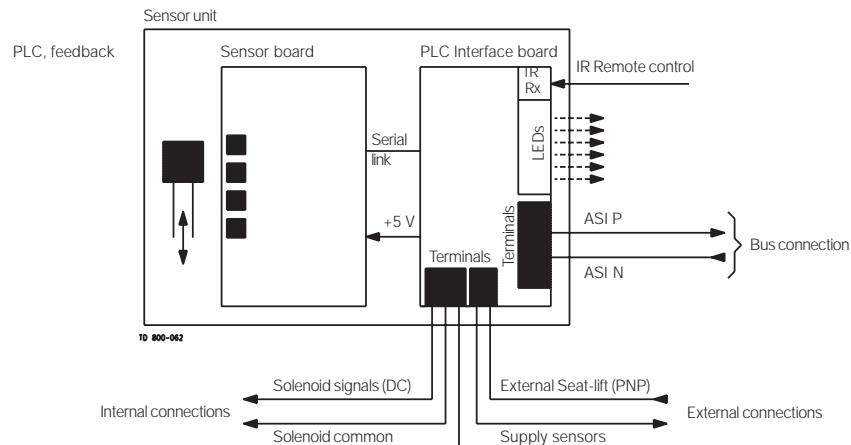
The **ThinkTop**[®] is designed to ensure optimum valve control in conjunction with Alfa Laval valves and it is compatible with most PLC systems (Programmable Logic Controllers) with AS-Interface.

The **ThinkTop**[®] can be equipped with 0-3 solenoid valves. The solenoids are electrically controlled by the AS-Interface and when activated the compressed air is activating the air actuator. All solenoids have build-in throttle function on both air inlet and outlet which means that it is possible to control the opening and closing time of the air actuator. The solenoids are also equipped with a manual hold override.

Visual LED lights are constantly indicating the status of the unit: Valve positions, solenoid activated, setup and local fault indication etc.

The **ThinkTop**[®] is characterized by a simple and modular design. It is exchangeable and is prepared for upgrading.

3.1.1 "No Touch" sensor system



Type: Alfa Laval "No Touch" System

For wire connections: See section 4.4 "Electrical connection, internal".

Features

- Tolerance programmes.
- Self adjustment programme (SRC/ARC valves only).
- Built-in maintenance monitor.
- Setup by internal pushbuttons or remote control (IR Keypad).
- Setup and local fault supervision.
- Setup saved at power shutdown.
- Visual LED Indicator lights.

Sensor System

Unique "No Touch" sensor system without any mechanical sensor adjustments. A magnet is mounted on the valve stem and the magnetic field (axial) is detected by sensor chips inside the sensor unit. The measuring angle from each chip is used to locate the current position of the valve stem with an accuracy of ± 0.1 mm. Note that the distance to the magnet can be $5 \text{ mm} \pm 3 \text{ mm}$.

Feedback signals

The sensor system can be used for 3 feedback signals + 1 status signal = 4 feedback signals. (Two of the feedback signals can be used for external sensors if necessary).

The status signal is used for detection of the following three conditions:

- A set-up is in progress.
- Internal error.
- Maintenance is required (based on time and/or the self adjustment programme).

Tolerance programme:

Individual according to valve types.

- Type 1: SRC/ARC and Series 700 valves.
- Type 2: LKB (LKLA-T).
- Type 3: *Unique*, SMP-SC Spillage-Free, SRC-PV and AMP.
- Type 4: SMP-SC, SMP-TO, SMP-BC, SMP-BCA and SBV.
- Type 0: (Preset) All Parameters Set To Default (also valid for MH Koltek valve and SMP-EC (seat-lift indication not possible for SMP-BC)).

Preset and reset values: Tolerance programme No. 0 (± 5 mm) and all functions are disabled.

NOTE! Important to select the right tolerance programme.

Self Adjustment (SRC/ARC valves only)

The self adjustment feature is an exceptional aspect of the *ThinkTop*® design. A programme can be activated to allow an adjustment of the tolerance band if the seals in the valve are being compressed or are worn. When the tolerance band of the unit has been adjusted 0.3 mm, an alert warning will appear in the form of a status signal and a flashing maintenance LED. After 0.5 mm adjustment an alarm warning appears: Loss of feedback signal, status signal and steady maintenance light indicating a minimum of seal left requiring a replacement of the seal.

Built-in Maintenance Monitor

The unit can be preset to indicate when the time for maintenance of the valve has been reached. A status signal and flashing maintenance LED can be programmed to return after 3, 6, 9 or 12 months or more.

3.1.2 Technical specifications sensor system

Sensor accuracy: $\pm 0,1$ mm.
 Distance to magnet: 5 ± 3 mm.
 Stroke length: 0.1 - 80 mm.
 Electrical connection: Direct cable gland entry (hard wired)
 PG11 ($\varnothing 4$ - $\varnothing 10$ mm).

Terminals

The terminal row of the sensor unit is equipped with screw terminals for both internal as well as external cables and wires. The terminals are suitable for wires up to 0.75 mm² (AWG 19).

Power Supply

The power supply to the complete unit is taken from the AS-Interface.

Supply voltage: 29.5 - 31.6 V DC.
 Supply current: Max. 45 mA (for sensor unit alone)
 (excluding current to the solenoids and the external proximity switches).

The fulfilling of the UL requirements in UL508 requires that the unit is supplied by an isolating source complying with the requirements for class 2 power units (UL1310) or class 2 and 3 transformers (UL1585).

Feedback signals

Signals transmitted over the AS-Interface BUS to the AS-Interface master PLC.

External sensors

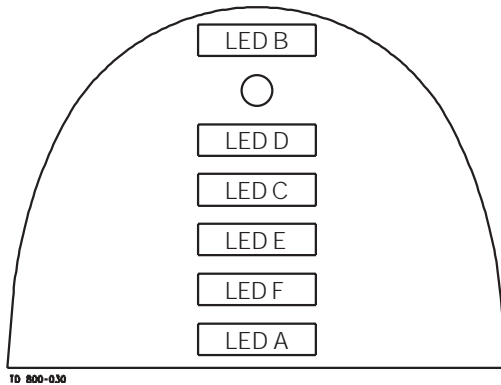
The external sensors are used for seat-lift supervision when seat-lift can not be internally detected. The sensors get their supply voltage from the terminal row. The output signals from the sensors are connected to two inputs on the terminal row on the internal sensor unit. If the actual setup is set for internal seat-lift, the corresponding external signal is not used, otherwise the external signal logically controls the corresponding feedback to the PLC.

Supply voltage: As specified for the AS-Interface (typical 24 VDC).
 Supply current: Max. 15 mA per sensor.
 Type of sensor: Only 3-wire sensor PNP.
 Sensor cable length: Max. 3 m.

ASi-bus bit assignment

For the AS-Interface version, the following bit assignment will be used:

| | |
|---|---------------------------------|
| Input bit 0 - feedback # 1 Closed position | Output bit 0 - Not connected |
| Input bit 1 - feedback # 2 Open position | Output bit 1 - Solenoid valve 1 |
| Input bit 2 - feedback # 3-4 Seat 1 or 2 position | Output bit 2 - Solenoid valve 2 |
| Input bit 3 - feedback # 5 Status | Output bit 3 - Solenoid valve 3 |

ThinkTop® Visual Indications**LED Indications**

| | |
|------------------------|----------|
| "Open valve" | (Yellow) |
| IR-Receiver | |
| "Setup/Internal fault" | (Red) |
| "Seat-lift 1/2" | (Yellow) |
| "Solenoid valves" | (Green) |
| "Maintenance" | (Orange) |
| "Closed valve" | (Yellow) |

Note: If the programmer wishes to detect a physically closed valve position in an "open valve" sensor position, then there is no longer any consistence between the sensor valve detection position and the visual indications of the *ThinkTop®*.

Status signal (feedback # 5) Input bit 3:

The status signal is used for five purposes:

- To indicate that set-up is going on (LED D).
- To indicate an error condition (LED D), (flashing = software error), (steady = hardware error).
- To indicate that the time for maintenance has been reached (LED F).
- To indicate if there is a conflict in the self adjustment programme (LED F).

Default slave address: 0

I/O code: 7 (4 bit bi-directional)

I/D code: F (slave without profile)

P = F.7.

For wire connections: See section 4.4 "Electrical connection, internal".

No. of nodes: Max. 31 *ThinkTop®* on a single master/gateway.

3.1.3 Technical specifications solenoid valves**Solenoid signals**

Signals transmitted over the AS-Interface BUS to the AS-Interface master PLC.

Internal connections

Terminals for connection of the solenoids mounted internally in the control head.

The number of solenoids actually mounted in the control head could be 0 - 3.

The signals are taken directly from the terminal row.

| Technical specifications | |
|---|---|
| Up to 3 solenoid valves in each unit. | |
| Type | 3/2 or 5/2 valve (only possible with one 5/2 valve). |
| Air supply | 300-900 kPa (3-9 bar). |
| Filtered air, max. particles or dirt | 0.01 mm. |
| Max. flow | 180 l/min. |
| Max. oil content | 1.0 ppm. |
| Max. water content | 0.0075 kg/kg air. |
| Throughput | ø2.5 mm. |
| Air restriction (throttle function) air inlet/outlet. | |
| Manual hold override. | |
| External air tube connection | ø6 mm or 1/4" (specify when ordering). |
| Nominal voltage | 24 VDC. |
| Nominal power | 1.0 W. |
| Silencer/filter *) | Connection possible via ø6 mm or 1/4". |
| Internal connections (solenoids) | |
| The solenoid drivers can reduce the solenoid power by PWM after the activation time. The PWM function is enabled by a jumper (12, 13). The number of solenoids actually mounted in the Control head could be 0 - 3. | |
| Nominal voltage | 24 VDC. |
| Nominal power | 1.0 W. |
| Output voltage | Must match the selected type of ThinkTop®. |
| Load current | Max. 100 mA per solenoid. Max. current from any number of energized output stages is 200 mA. |
| Voltage drop | Max. 3 V at 50 mA. |
| Activation time | 60 ± 10 ms (time with full power if PWM is enabled). |
| PWM duty cycle | 40% (after activation time if PWM is enabled). |
| PWM frequency | 2 - 5 kHz. |
| Materials | |
| Plastic parts | Nylon PA12. |
| Steel parts | Stainless steel AISI 304 and 316. |
| Seals | Nitrile (NBR), EPDM rubber for SMP-EC activator stem. |
| *) Note! Filter recommended in tropical regions. | |

3.1.4 Micro environment demand specifications

| | | |
|-------------------------|--|------------------------|
| Temperature | | |
| Working: | -20°C to +85°C | IEC 68-2-1/2 |
| Storage: | -40°C to +85°C | IEC 68-2-1/2 |
| Temperature change: | -25°C to +70°C | IEC 68-2-14 |
| Vibration | | |
| | 10-55 Hz, 0.7 mm 55-500 Hz, 10g 3 x 30 min, 1 octave/min | IEC 68-2-6 |
| Drop test | | |
| | | IEC 68-2-32 |
| Humidity | | |
| Constant humidity: | +40°C, 21 days, 93% R.H. | IEC 68-2-3 |
| Cyclic humidity: | +25°C/+55°C 12 cycles | IEC 68-2-30 |
| (working) | 93% R.H. | |
| Protection class | | |
| | IP67 | IEC 529 |
| Input threshold | | |
| Voltage/current: | Type 1 input requirements | EN 61131-2 |
| EMC Directive | | |
| | 89/336/EEC | EN 50081-1, EN 50082-2 |
| AS-Interface | | |
| | Version 2.11 *) | EN 50295 |
| UL Approval | | |
| | 8-30 VAC/VDC, Class 2 input, 45 mA max. output | UL 508-E203255 |

*) Max. 31 ThinkTop® on a single master/gateway.

Step 1

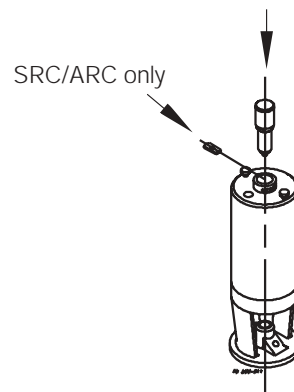
- **Always** read the technical specifications thoroughly (see chapter 3).
- **Always** have the *ThinkTop*® electrically connected by authorized personnel.
- **Never** install the *ThinkTop*® before valve or relay is in a safe position.

Step 2

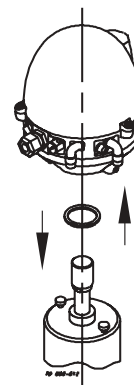
1. Fit the air fittings on actuator if not mounted.
2. Fit the activator stem (magnet) and tighten **carefully** with a spanner.

NOTE!

The *ThinkTop*® for the SMP-EC valve has a longer activator stem going through the shell. Remember O-ring.

**Step 3**

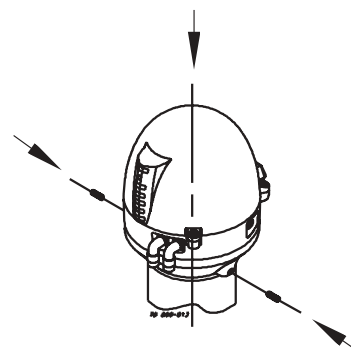
1. Place the *ThinkTop*® on top of the actuator.
2. Make sure X-ring is mounted.

**Step 4**

1. Ensure that the unit is correctly mounted by pressing down on top of the *ThinkTop*®.
2. Tighten the two Allen screws **carefully**.
3. Turn the actuator to have LEDs in a front view.

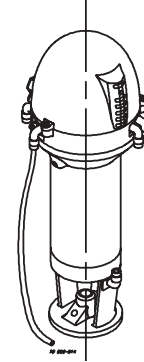
NOTE!

After a relevant period of time after installation (eg. two weeks) it is recommended to check that all connections are properly tightened.



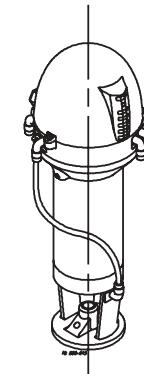
Step 5

Fit the $\varnothing 6$ mm (1/4") air tubes to *ThinkTop*[®] (see drawing "Air connections" later in this chapter).



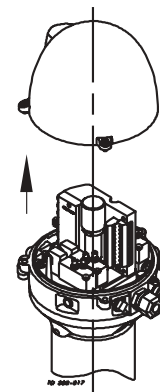
Step 6

Fit the air tubes to the actuator (see drawing "Air connections" later in this chapter).



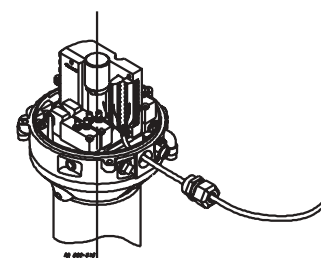
Step 7

Untighten the three screws and pull off cover of *ThinkTop*[®].



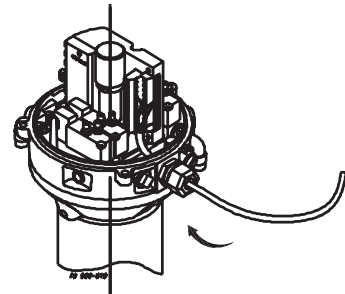
Step 8

1. Install cable (if not present) through the cable gland.
2. Connect the *ThinkTop*[®] electrically (see section 4.4 "Electrical connection, internal").



Step 9

Make sure the cable gland is completely tightened.

**Step 10**

Set up the *ThinkTop*[®] (see chapter 5).

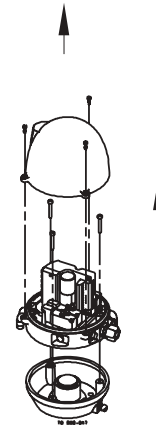
NOTE!

The unit can be set up with the cover installed by using the IR keypad. To energize the valve, use a separate air tube or be in radio contact with the control room.

Step 1

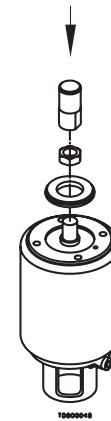
1. Remove the cover by loosening the three cross recess screws.
2. Separate the adapter from the base by loosening the three recess screws on top of the base.

Installation on air actuators:



Step 2

1. Fit air fittings on actuator.
2. Position packing retainer in recess on actuator top.
3. Fit counter nut and indicator (magnet) on actuator rod. Engage approx. 1/4" thread. Tighten counter nut and indicator with two wrenches.



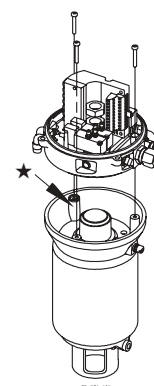
Step 3

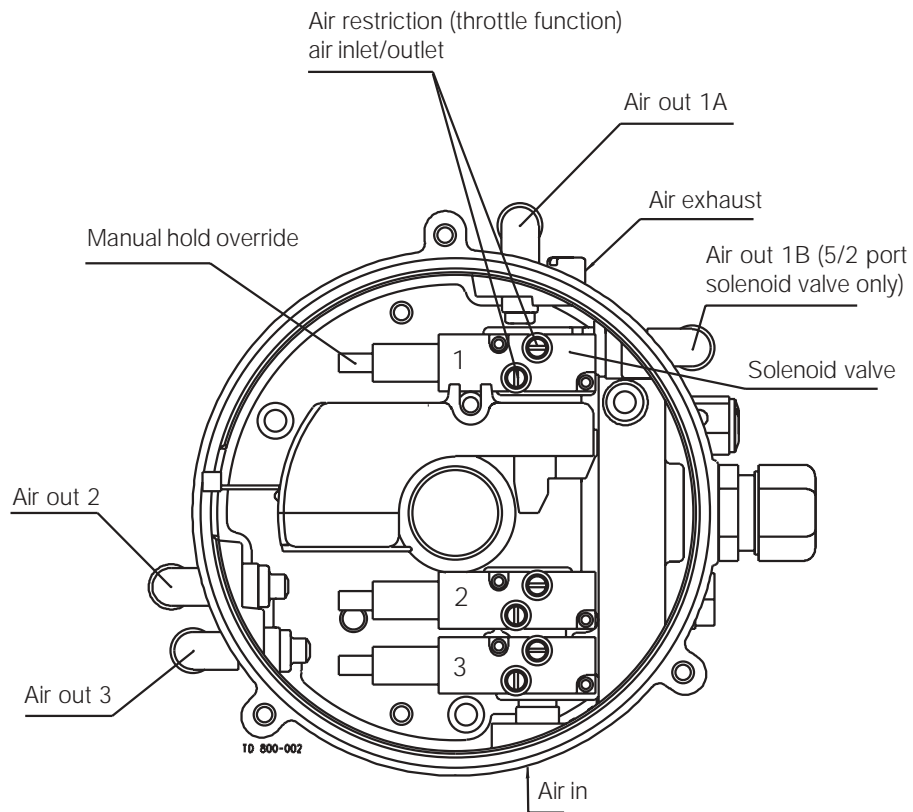
1. Place the two O-rings in the grooves in the bottom of the adapter. Then place the adapter on the actuator top. The small O-ring must be positioned over the air hole on the actuator.
2. Fasten the adapter with the four 5/16" Allen screws.

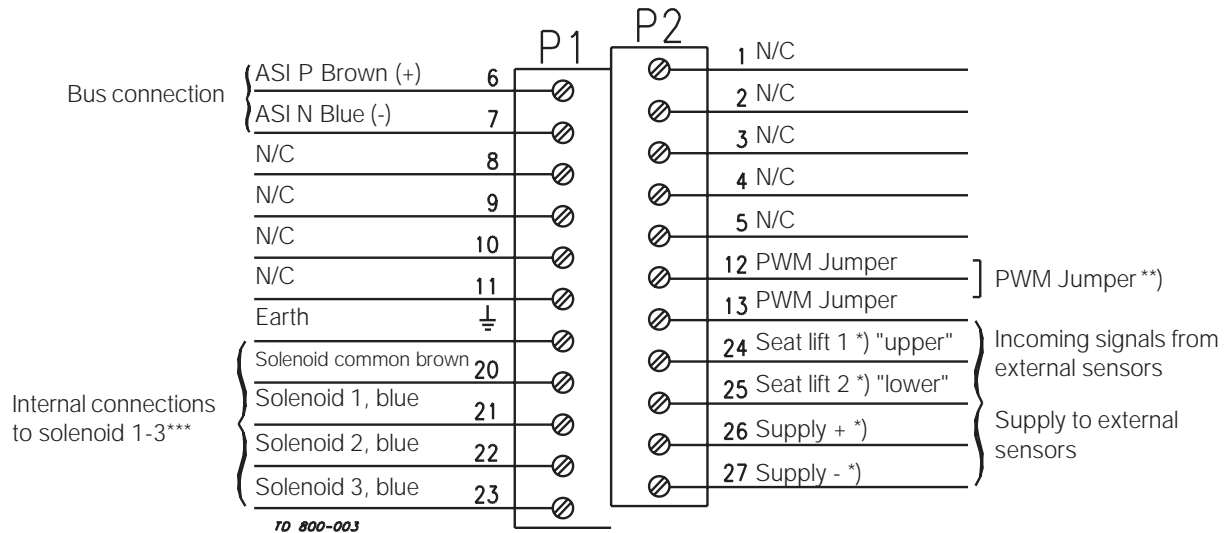


Step 4

Mount the base on the adapter in the position needed (can be rotated 120° in both directions). Note that one of the screw towers on the adapter has a guide recess (see ★ on drawing).







*) **Note!**

- Terminals 24, 25, 26 and 27 can be used for external seat lift sensors as well as for any digital input. Always use an external PNP sensor.
- Two external signals can be connected, they are associated with feedback signal 3 (seat lift 1) and 4 (seat lift 2). External sensor must always be a 8-30 VDC PNP 3 wire sensor. Connect (-) common on terminal 27, and (+) common on terminal 26. The signals from the external sensors are associated as follows: sensor signal on terminal 24 (seat lift 1) associated with feedback 3 (seat lift 1), and sensor signal on terminal 25 (seat lift 2) associated with feedback 4 (seat lift 2).

***) **Note!**

Jumper present = PWM. See section 3.1.3 "Technical specifications solenoid valves".

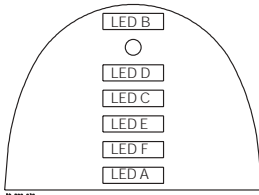
***) **Note!**

Internal connections: Terminals for connection for the solenoids mounted internally in the control head. The number of solenoids actually mounted in the control head could be 0 - 3. The signals are taken directly from the terminal row.

- Notes:**
- O - Scroll across, no change
 - _____ - Notes Requires Key Function
 - - - - - Notes Automatic Progress as Indicated

- General:**
1. Flashing IND means no value set.
Steady IND means value set as shown.
 2. Default is: Step 2, Type 0 (+/- 5 mm)
Step 3-8 disabled
 3. Lamp Status Shown in []

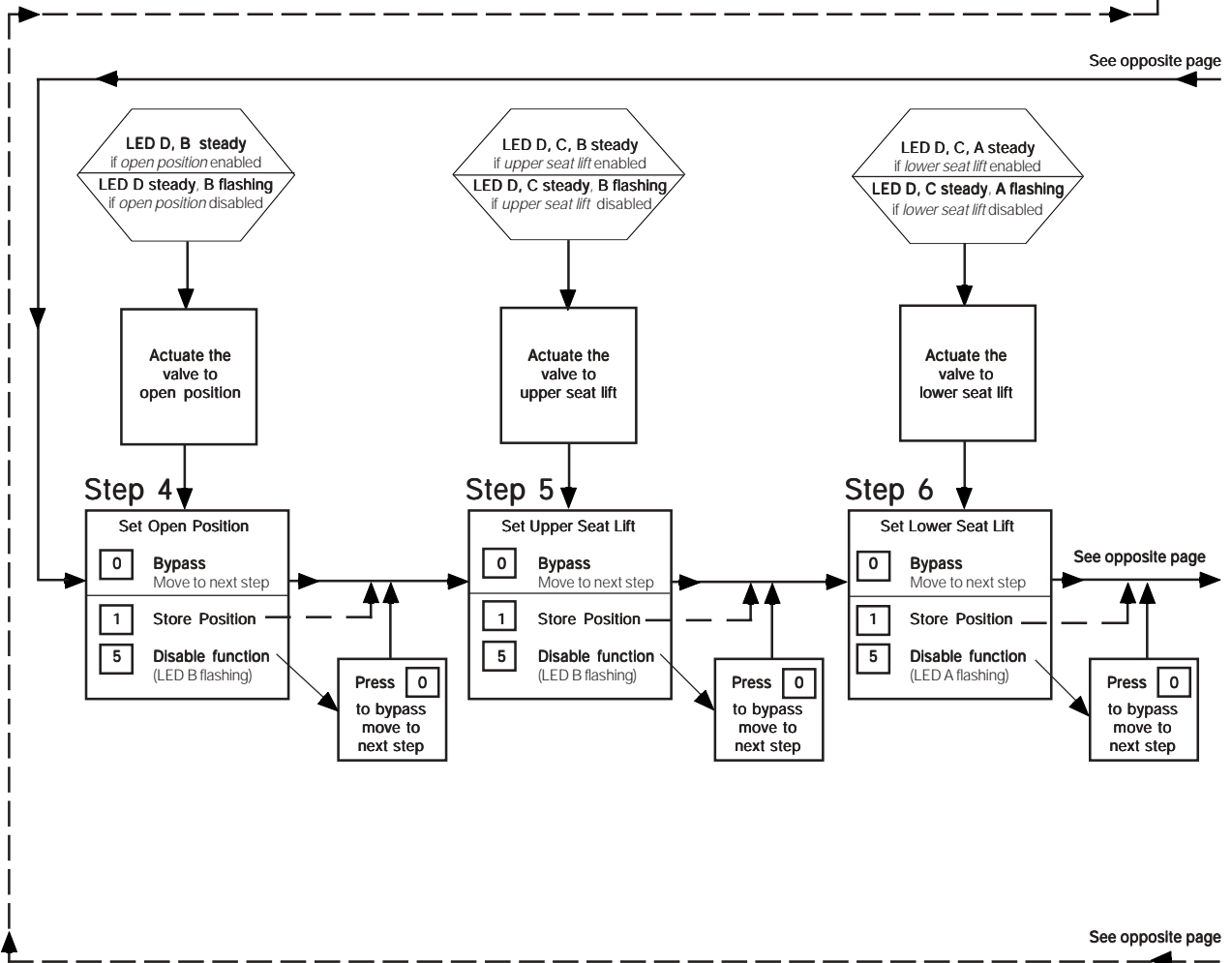
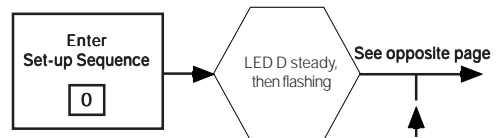
ThinkTop® Visual Indications

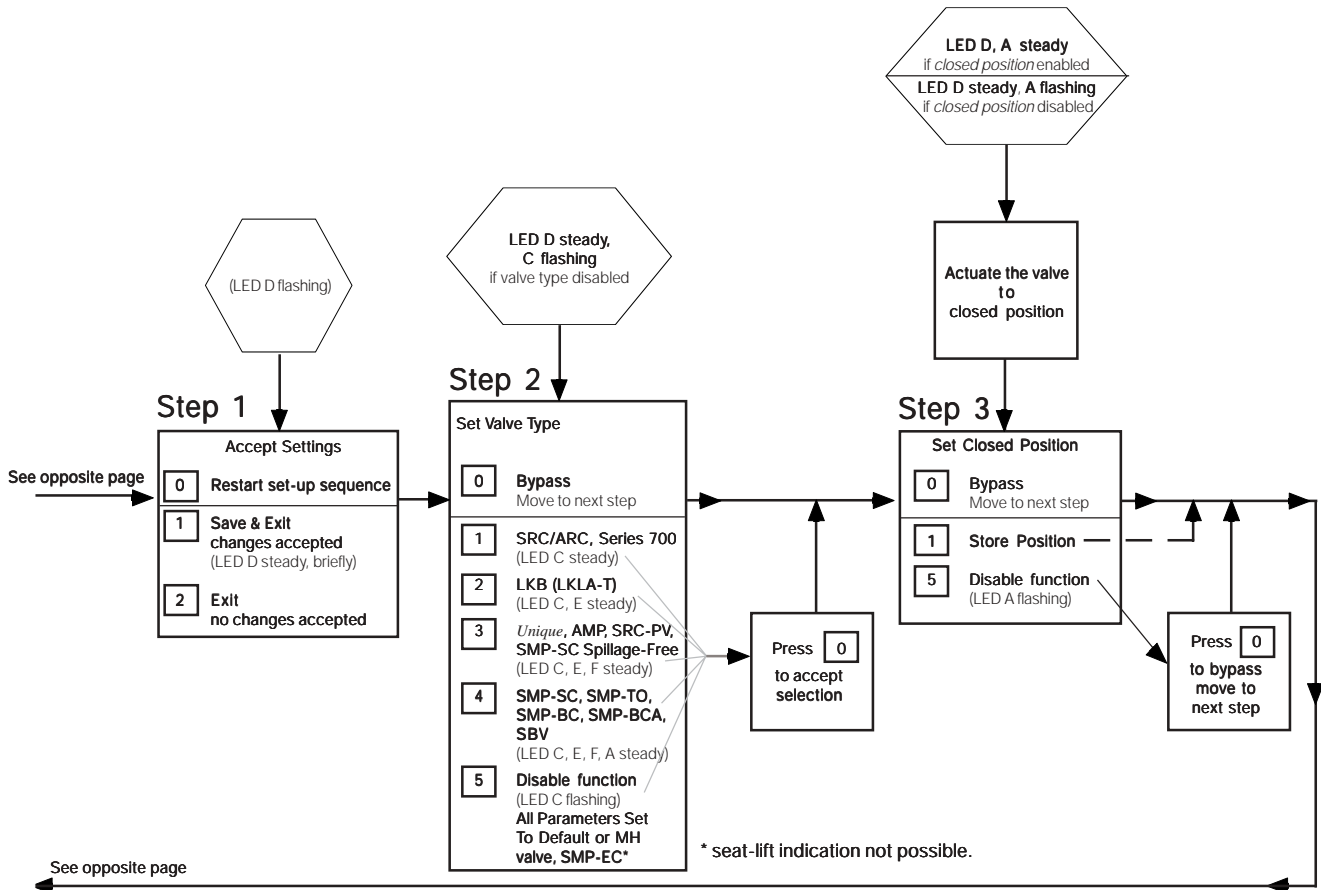


LED Indications

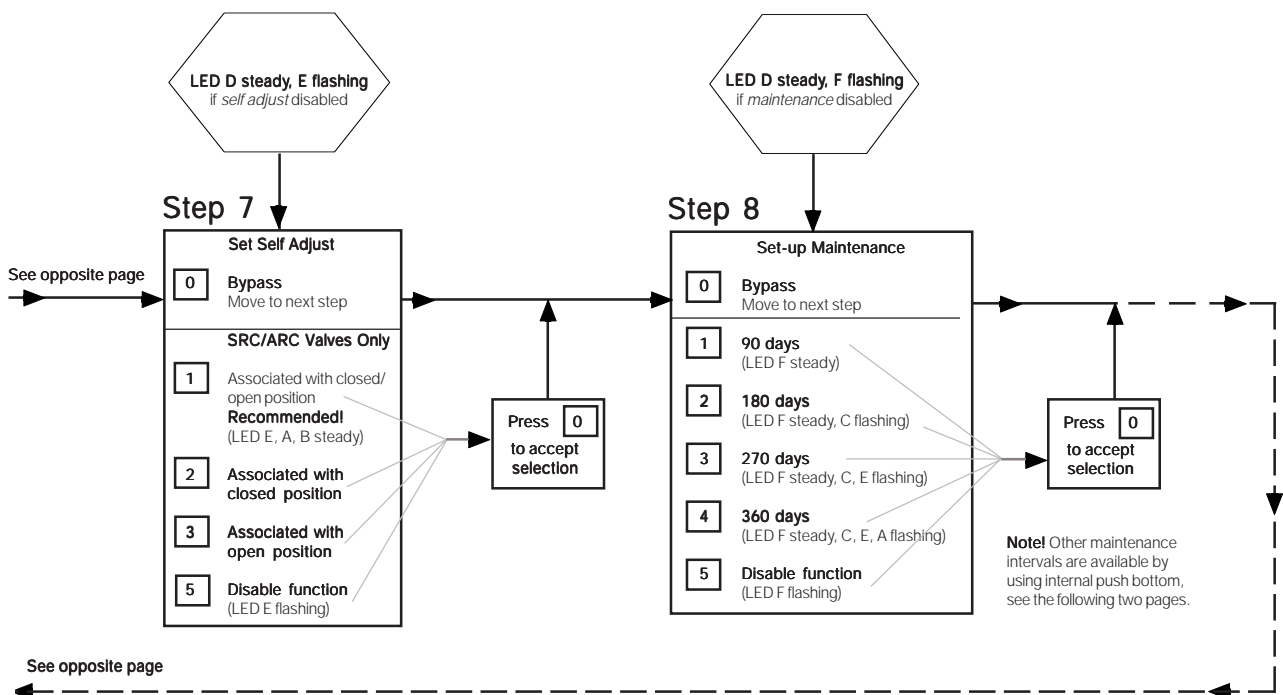
- "Open valve" (Yellow)
- IR-Receiver
- "Setup/Internal fault" (Red)
- "Seat-lift 1/2" (Yellow)
- "Solenoid valves" (Green)
- "Maintenance" (Orange)
- "Closed valve" (Yellow)

4. [D] IND active during set-up.
 - Flashing in step 1,
 - Steady in all other steps.
 or during operations, error condition
 - Steady showing hardware fault
 - Flashing showing software fault
5. Timeout: A 60 second time-out is started as soon as any button(s) are released. If no button is pressed during the time-out time, go to normal condition (cancel & exit).
6. SRC/ARC valves: Self-adjust (step 7) must be activated. If you choose NOT to use the self-adjustment programme, Alfa Laval recommends to use the valve type 4 (step 2), instead of type 1 (bigger tolerances).





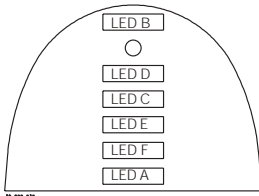
Note! Remote distance keypad = ThinkTop® 0-300 mm.



- Notes: | - Scroll across, no change
 _____ - Notes Requires Key Function
 - - - - - - - Notes Automatic Progress as Indicated

- General: 1. Flashing IND means no value set. Steady IND means value set as shown.
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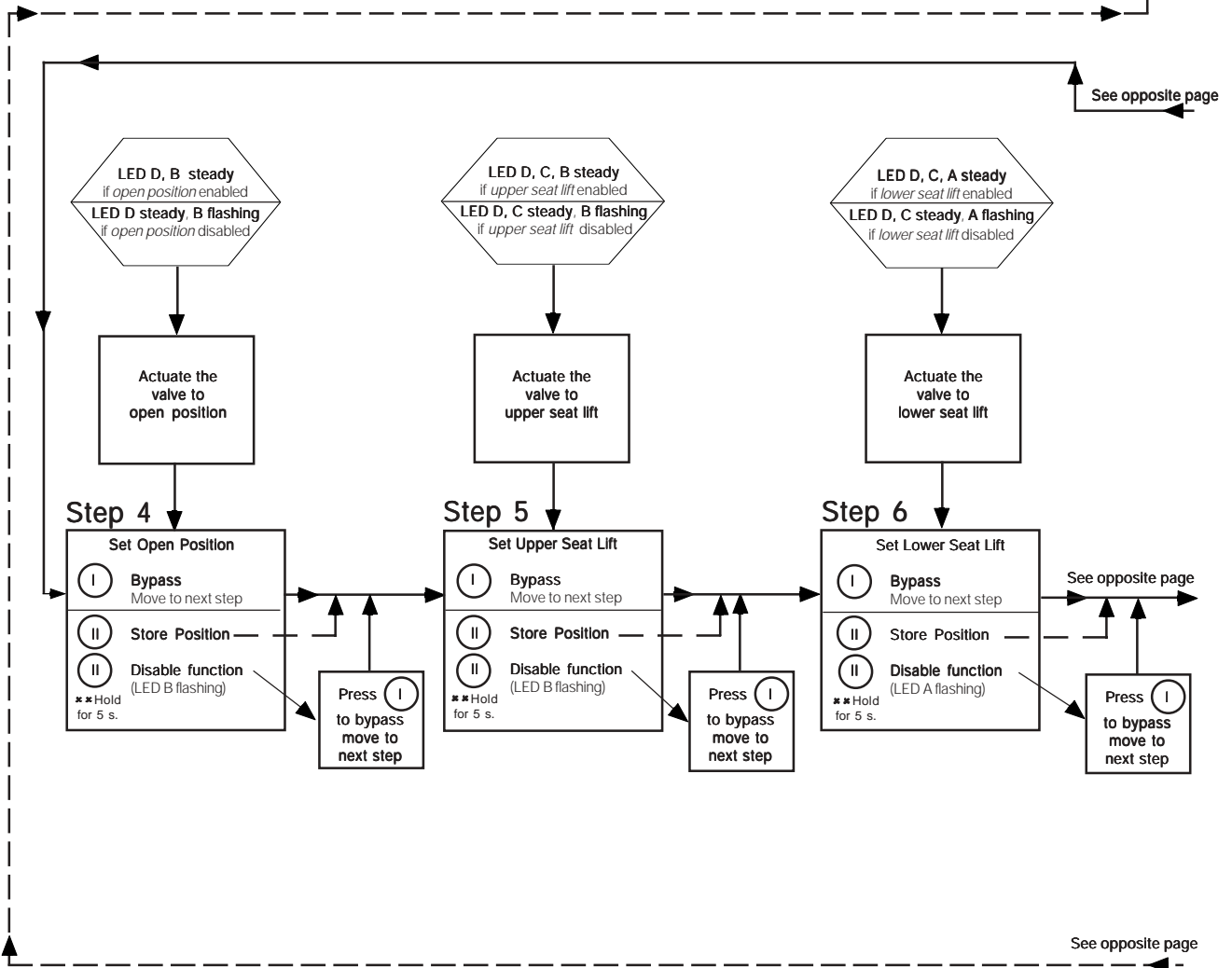
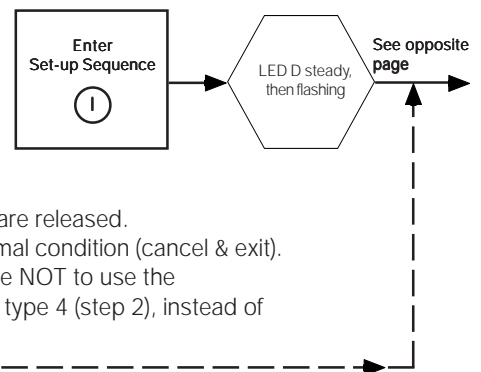
ThinkTop® Visual Indications

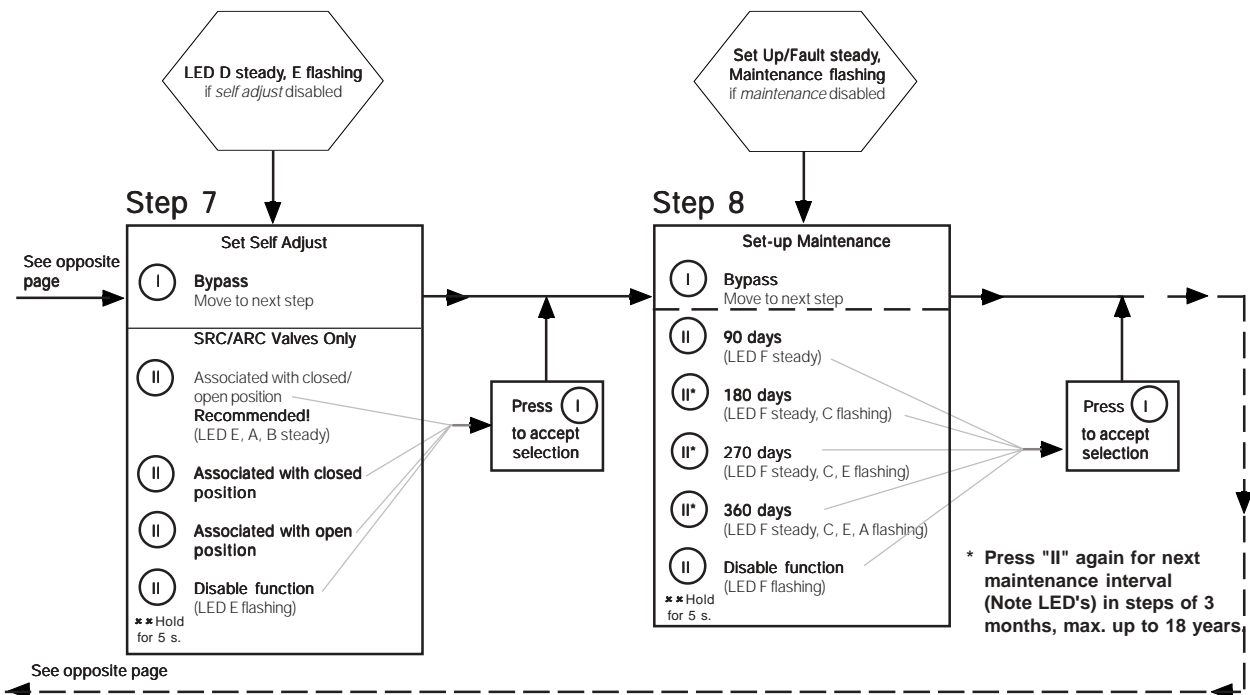
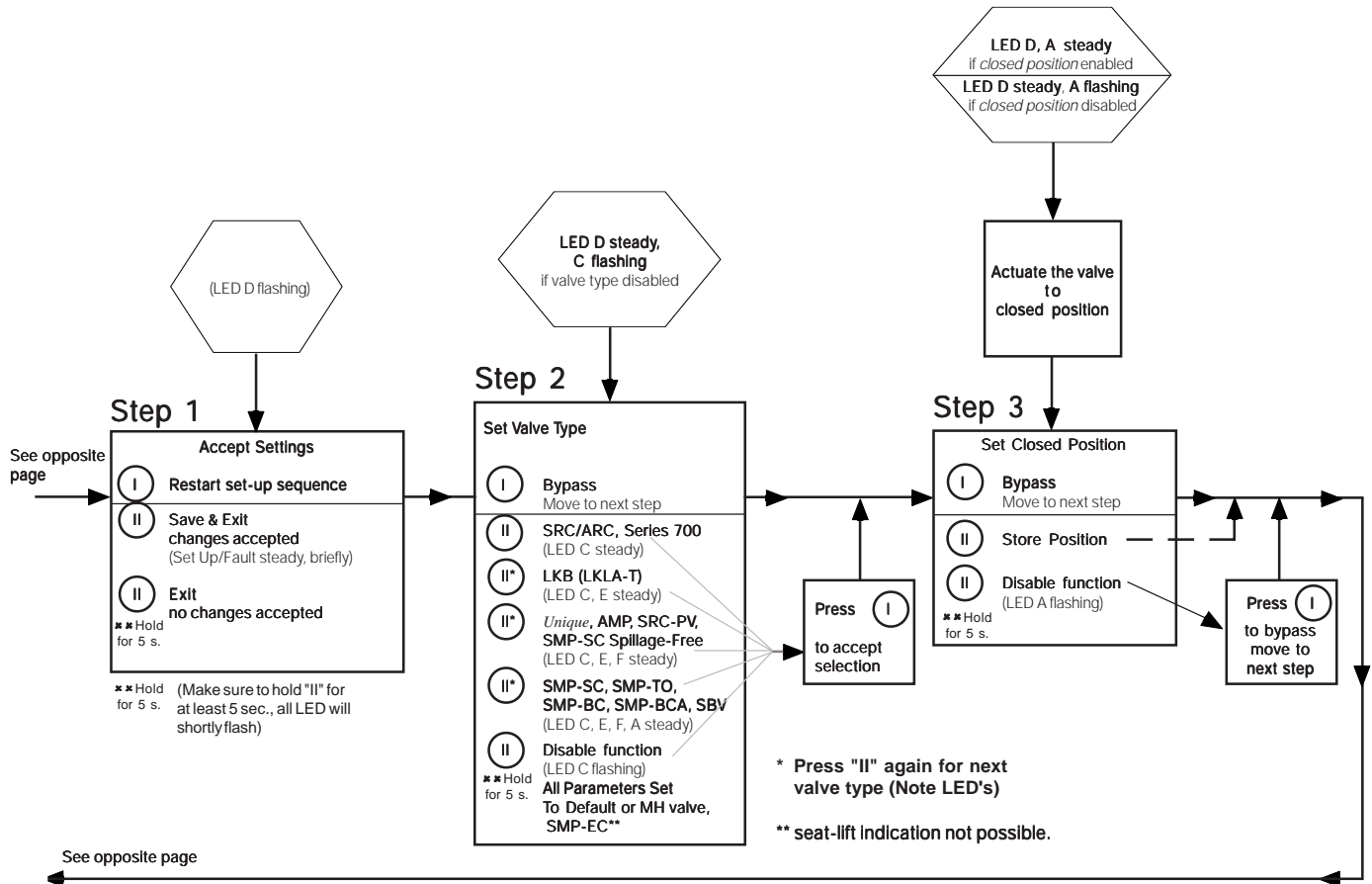


LED Indications

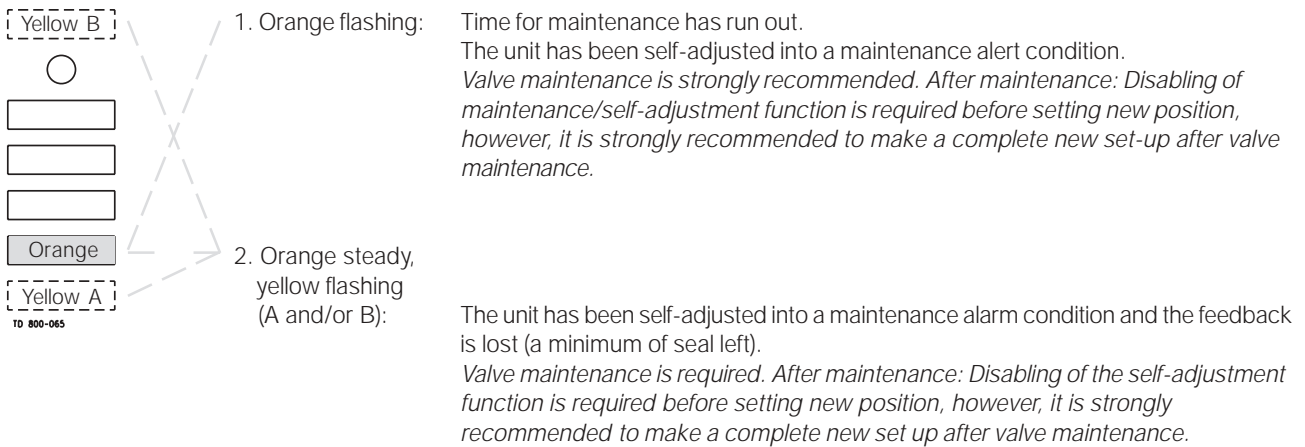
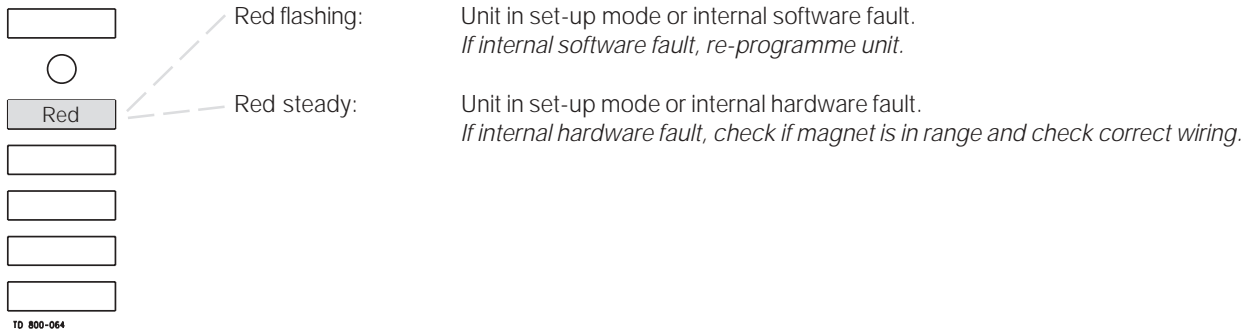
| | |
|------------------------|----------|
| "Open valve" | (Yellow) |
| IR-Receiver | |
| "Setup/Internal fault" | (Red) |
| "Seat-lift 1/2" | (Yellow) |
| "Solenoid valves" | (Green) |
| "Maintenance" | (Orange) |
| "Closed valve" | (Yellow) |

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Below is stated the meaning of the LEDs' indications for fault finding in connection with the operation of the *ThinkTop*[®].

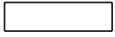
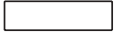


NOTE!

The maintenance indicator lighting up, and an open or closed light flashing.....

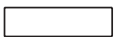
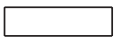
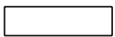
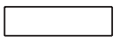
= Note the following:

- Self-adjustment programme is only valid for **SRC/ARC** valves, **do not use the programme for other valve types.**
- Use tolerance/valve type 1.
- In conjunction with valve type change-over; 21, 22, 31 and 32, the open position must be defined as the upper sensor position (when the magnet is in the highest position).
- A loose top, magnet holder or sensor system can also generate the alert/ alarm condition.
- Removing a *ThinkTop*[®] with self-adjust activated, will immediately generate an alarm condition! If the *ThinkTop*[®] has to be removed, not because of a valve maintenance issue, but for some other reasons, and you want to store the already adjusted data - disable the self-adjust function before removing the *ThinkTop*[®] and enable it again once the *ThinkTop*[®] is back on the actuator.
- After valve maintenance a disabling of the self-adjustment function is required before setting a new position, however, it is strongly recommended to make a complete new set-up (disable all functions in step 2 valve type - and make a complete new set-up).



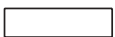
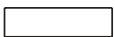
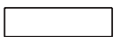
TD 800-064

Yellow steady: Position A (closed valve).



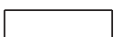
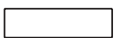
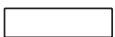
TD 800-064

Yellow steady: Position B (open valve).



TD 800-064

Yellow steady: Position C (Seat lift 1-2 or external sensors).



TD 800-064

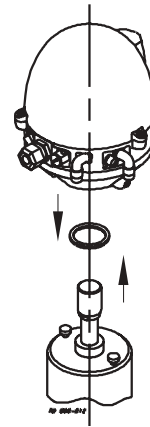
Green steady: Solenoid valves activated.

Note! During set-up LED lights have different functions.

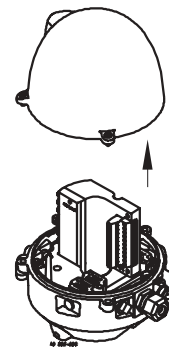
Study the instructions carefully.
 Handle scrap correctly.
 Always keep spare X-rings in stock.

Step 1

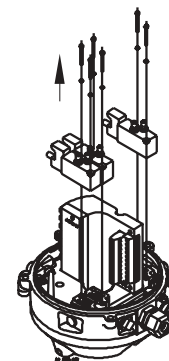
1. Remove the *ThinkTop*[®] from the actuator.
2. Pull out X-ring and replace it.

**Step 2**

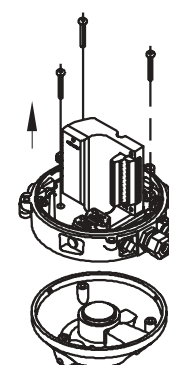
1. Untighten the three screws.
2. Pull off the *ThinkTop*[®] cover.

**Step 3**

1. Untighten screws.
2. Remove solenoid valves (up to 3) and replace them with new ones.

**Step 4**

1. To dismantle the adapter (the lower part of the *ThinkTop*[®]) from base (the middle part), unscrew the three screws.
2. Turn the lower part a little clockwise and pull.
3. Replace adapter if necessary.

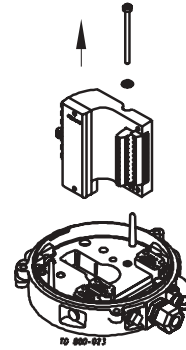


Note:
Turn banjo
connection!

*Study the instructions carefully.
Handle scrap correctly.
Always keep spare X-rings in stock.*

Step 5

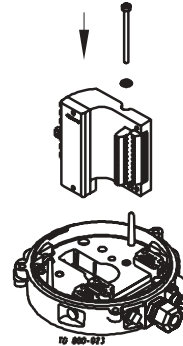
To remove the sensor unit untighten screw and pull out the sensor unit.



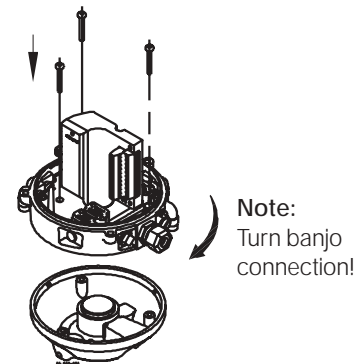
Study the instructions carefully.
 Handle scrap correctly.
 Always keep spare X-rings in stock.

Step 1

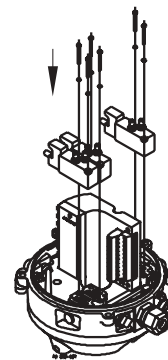
Place sensor unit in base and tighten screw (torque: 1 Nm).

**Step 2**

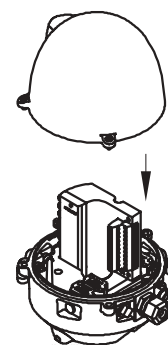
Assemble base with adapter by turning adapter a little anticlockwise and tighten the three screws (1.9 Nm).

**Step 3**

1. Replace solenoid valves (up to three) with new ones.
2. Tighten screws (0.2 Nm).

**Step 4**

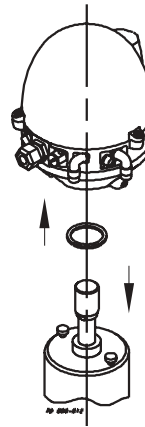
Replace cover of *ThinkTop*[®] and tighten the three screws (0.6 Nm).



Study the instructions carefully.
Handle scrap correctly.
Always keep spare X-rings in stock.

Step 5

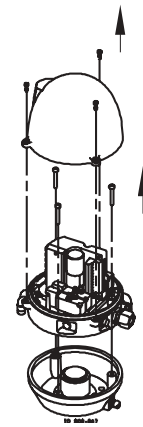
1. Replace X-ring.
2. Mount the *ThinkTop*® on actuator.



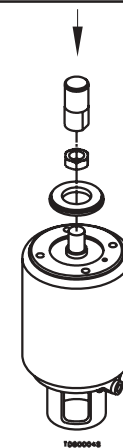
*Study the instructions carefully.
Handle scrap correctly.
Always keep spare X-rings in stock.*

Step 1

1. Remove the cover by loosening the three cross recess screws.
2. Separate the adapter from the base by loosening the three recess screws on top of the base.

Installation on air actuators:**Step 2**

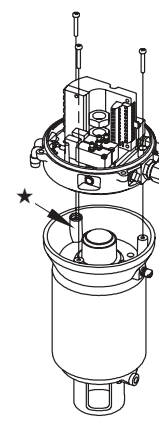
1. Fit air fittings on actuator.
2. Position packing retainer in recess on actuator top.
3. Fit counter nut and indicator (magnet) on actuator rod. Engage approx. 1/4" thread. Tighten counter nut and indicator with two wrenches.

**Step 3**

1. Place the two O-rings in the grooves in the bottom of the adapter. Then place the adapter on the actuator top. The small O-ring must be positioned over the air hole on the actuator.
2. Fasten the adapter with the four 5/16" Allen screws.

**Step 4**

Mount the base on the adapter in the position needed (can be rotated 120° in both directions). Note that one of the screw towers on the adapter has a guide recess (see ★ on drawing).



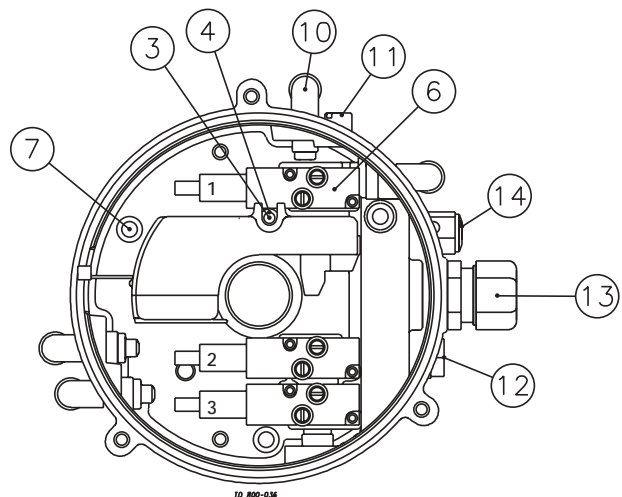
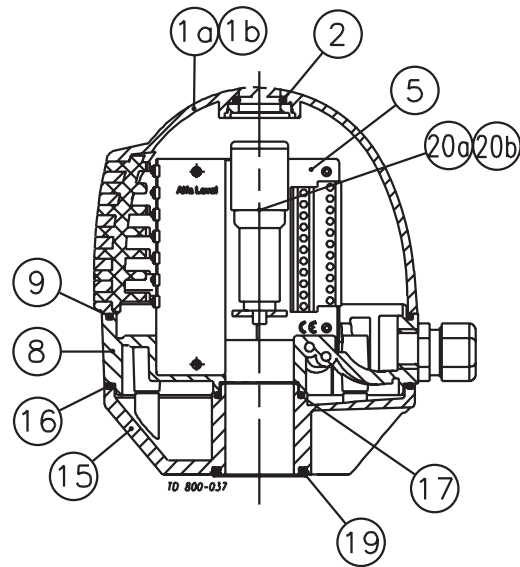
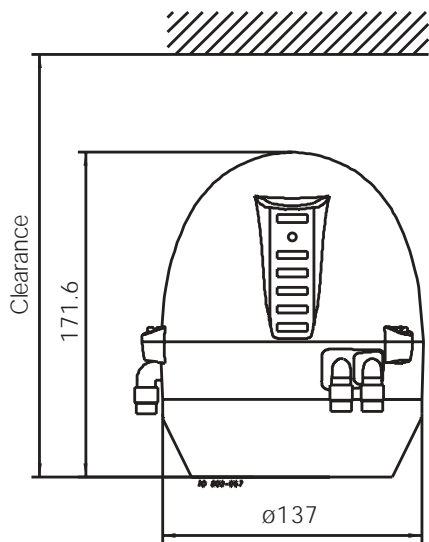
The drawing and the parts list include all items.

Parts List

| Pos. | Denomination |
|------|---|
| 1a | Shell |
| 1b | Shell |
| 2 | O-ring, NBR |
| 3 | Screw |
| 4 | Washer |
| 5 | Sensor unit |
| 6 | Solenoid valve |
| 7 | PT screw |
| 8 | Base |
| 9 | O-ring, NBR |
| 10 | Air fittings |
| 11 | Blow-off valve |
| 12 | Thread plug, PG7 |
| 13 | Cable gland, PG11 4-10 mm |
| 14 | Pressure control valve |
| 15 | Adapter |
| 16 | O-ring |
| 17 | O-ring |
| 18 | Allen screw |
| 19 | Special X-ring |
| 20a | Indication pin |
| 20b | Indication pin |
| 21 | O-ring, EPDM |
| 23 | 2 m. ASI drop cable (2 x 0.5 mm ²) with flat cable connector |
| 24 | Air fitting incl. O-ring |

Spare Parts

| Denomination | Item number |
|---|--------------|
| Sensor unit AS-Interface 29.5-31.6 VDC .. | 9612-5627-03 |
| Solenoid valve 3/2, 24 VDC | 9611-99-3324 |
| Solenoid valve 5/2, 24 VDC | 9611-99-3327 |
| Air fitting incl. O-ring, Ø6 mm | 9611-99-3404 |
| Air fitting incl. O-ring, 1/4" | 9611-99-3434 |



Note! This is the basic design.

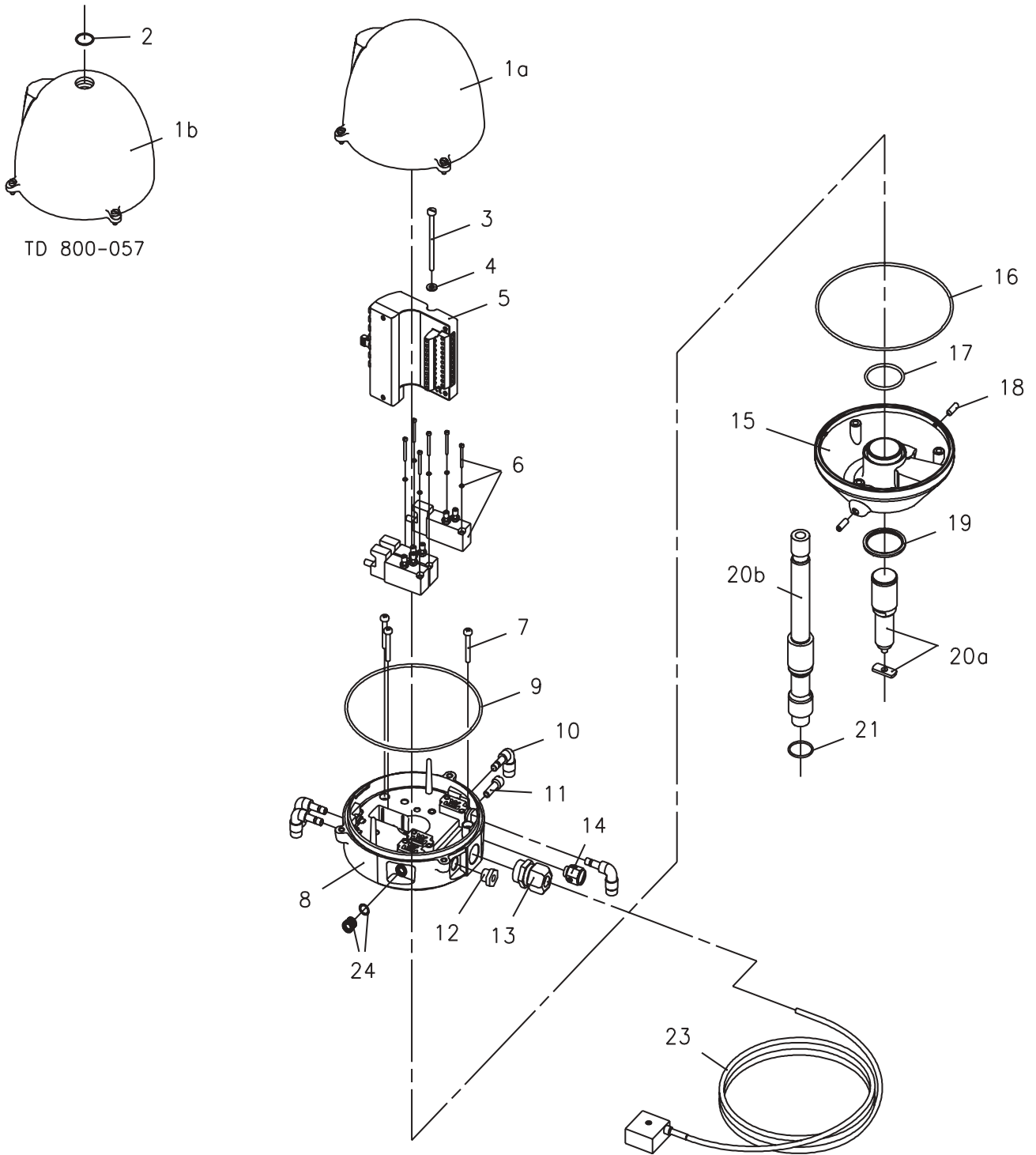
The clearance should be approximately:

- ø 225 x 250 (SRC NC, SMP-SC/-BC/-TO, Unique, Koltek MH, SBV, AMP)
- ø 225 x 320 (SRC NO)
- ø 225 x 300 (LKB (LKLA-T))

This page shows an exploded drawing of the ThinkTop®.

The drawing includes all items of the top unit.

Exploded Drawing



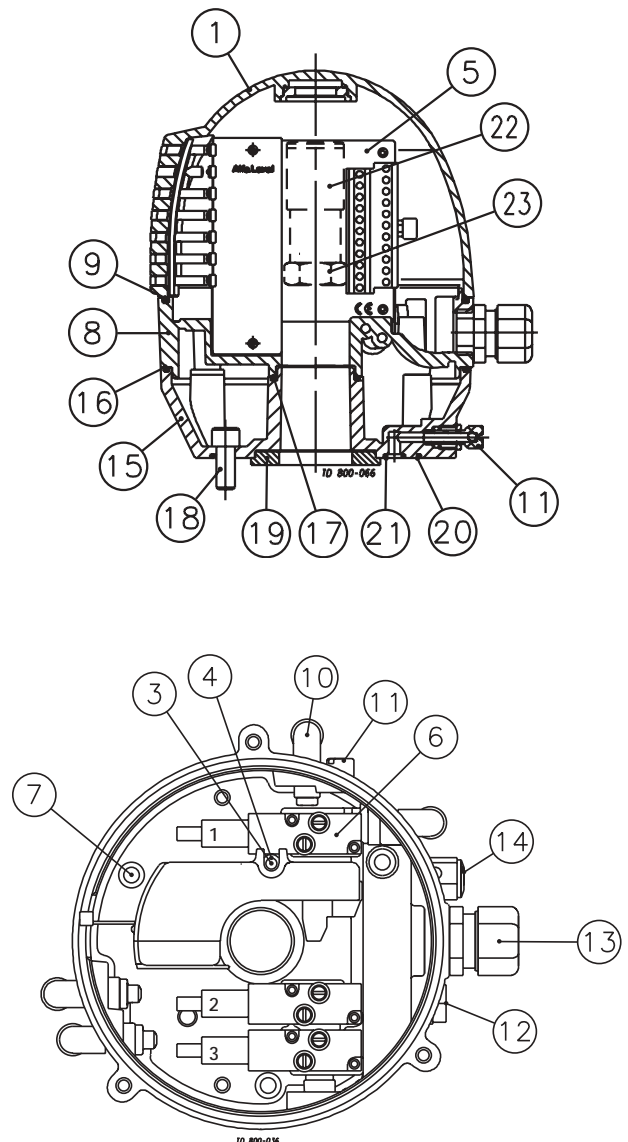
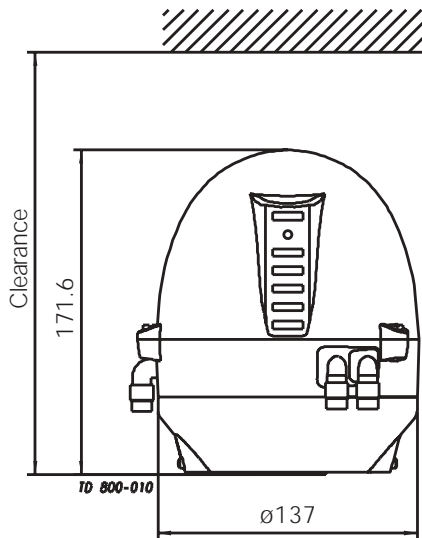
The drawing and the parts list include all items.

Parts List

| Pos. | Denomination |
|------|---|
| 1 | Shell |
| 3 | Screw |
| 4 | Washer |
| 5 | Sensor unit |
| 6 | Solenoid valve |
| 7 | PT screw |
| 8 | Base |
| 9 | O-ring, NBR |
| 10 | Air fittings |
| 11 | Blow-off valve |
| 12 | Thread plug, PG7 |
| 13 | Cable gland, PG11 4-10 mm |
| 14 | Pressure control valve |
| 15 | Adapter |
| 16 | O-ring |
| 17 | O-ring |
| 18 | Screw |
| 19 | Retainer |
| 20 | O-ring |
| 21 | O-ring, EPDM |
| 22 | Indicator pin |
| 23 | Nut |
| 25 | 2 m. ASI drop cable (2 x 0.5 mm ²) with flat cable connector |
| 26 | Air fitting incl. O-ring |

Spare Parts

| Denomination | 1/4" Air connec. |
|---|------------------|
| Sensor unit AS-Interface 29.5-31.6 VDC .. | 9612-5627-03 |
| Solenoid valve 3/2, 24 VDC | 9611-99-3324 |
| Solenoid valve 5/2, 24 VDC | 9611-99-3327 |
| Air fitting incl. O-ring, 1/4" | 9611-99-3434 |



Note! This is the basic design.

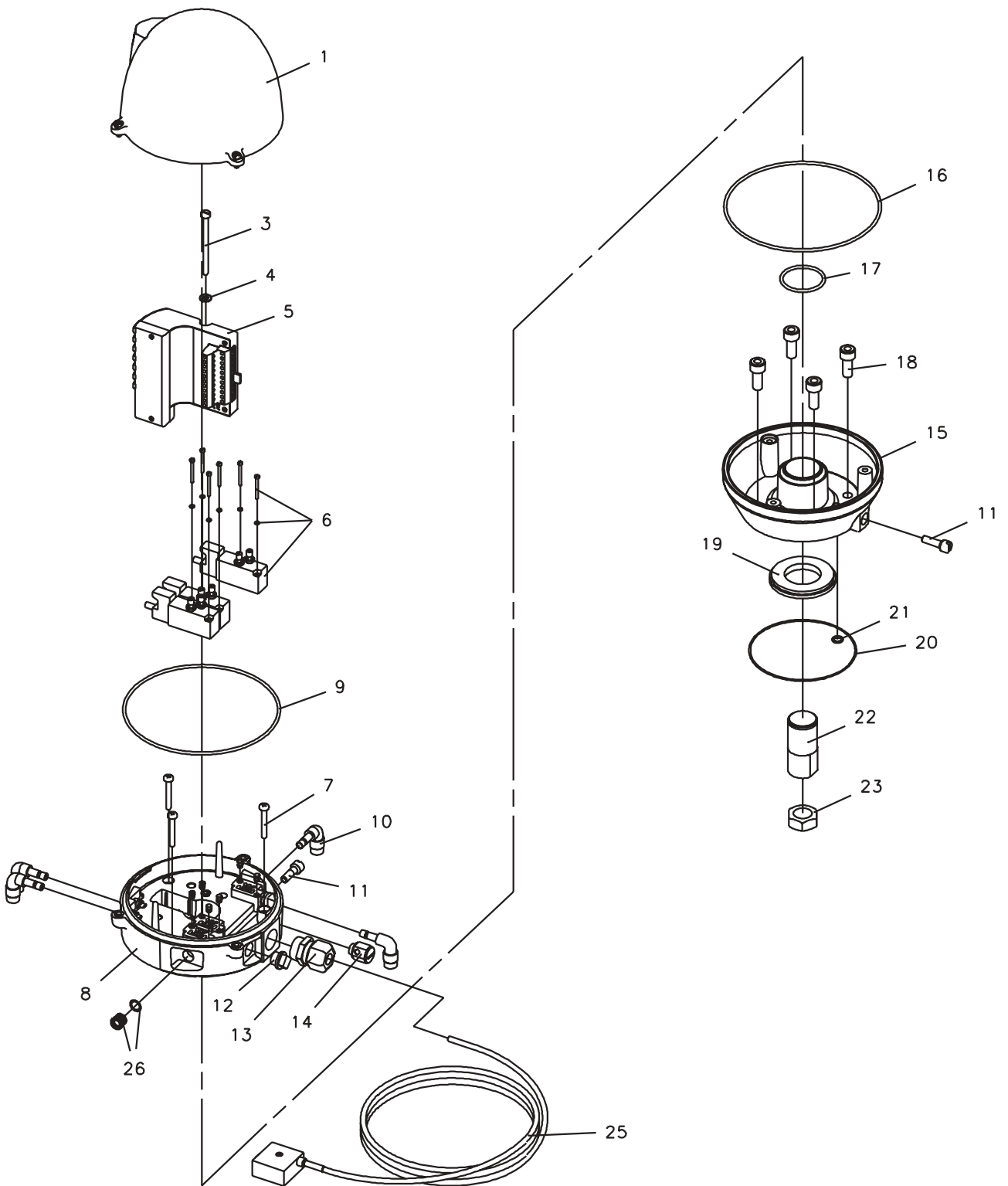
The clearance should be approximately:

- ø 225 x 250 (SRC NC, SMP-SC/-BC/-TO, *Unique*, Kolttek MH, SBV, AMP)
- ø 225 x 320 (SRC NO)
- ø 225 x 300 (LKB (LKLA-T))

This page shows an exploded drawing of the ThinkTop®.

The drawing includes all items of the top unit.

Exploded Drawing



TD 800-060

How to contact Alfa Laval

Contact details for all countries are continually updated on our website. Please visit www.alfalaval.com to access the information direct.